



Field Radiation Measurement Using Orpheus Robot



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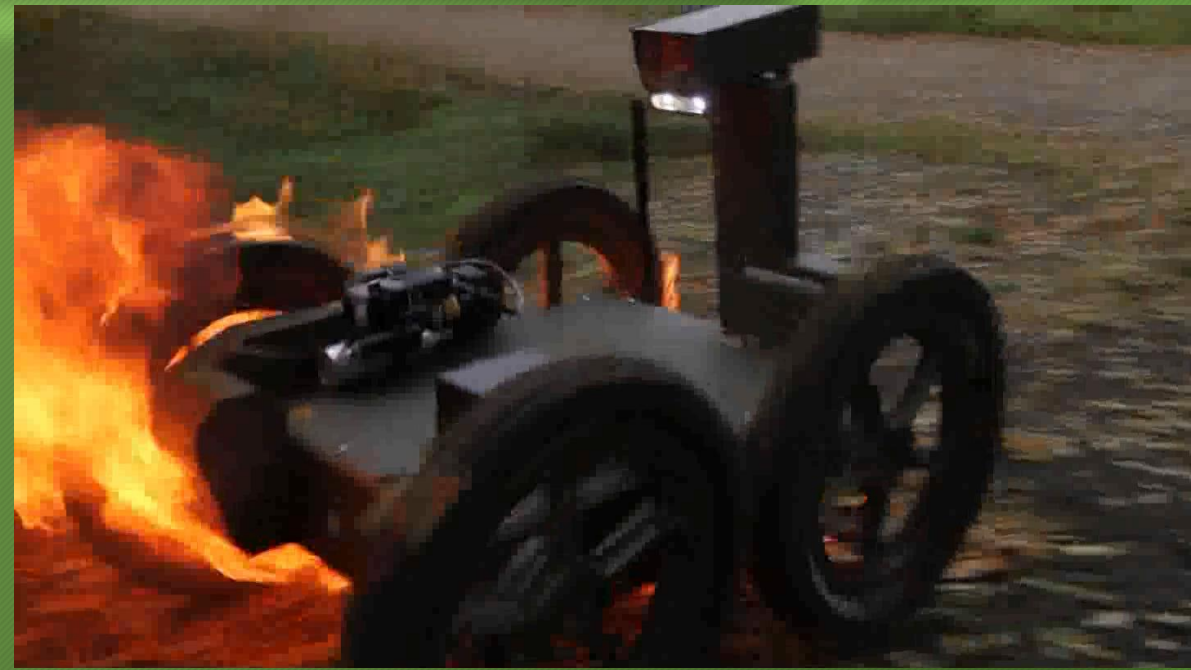
Two experiments

- I. Ground Radioactive Contamination Measurement Experiment
- II. Lost Radiation Sources Experiment
- cooperation with SURO (Statni ustav radiacni ochrany)

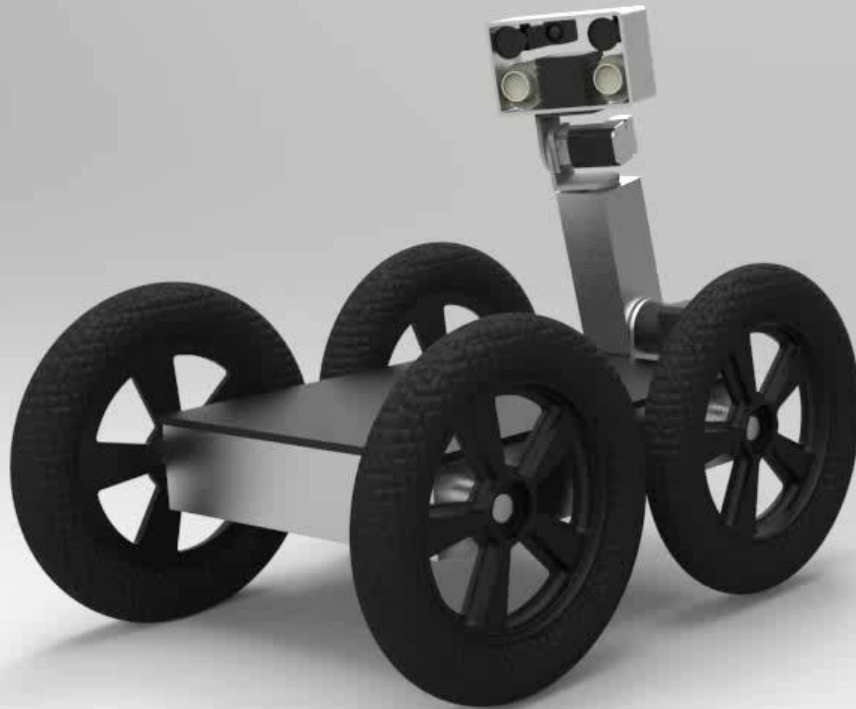


Orpheus-AC2

- CBRN robot
- rugged construction
- inside armored CBRN vehicle
- remote control from cockpit
- 2 chemical, 2 radiation sensors
- MIL-STD tests - environmental, EMC, special
- since 11/2013 in armament of Czech Army



ORPHEUS-X3



SENSORY HEAD

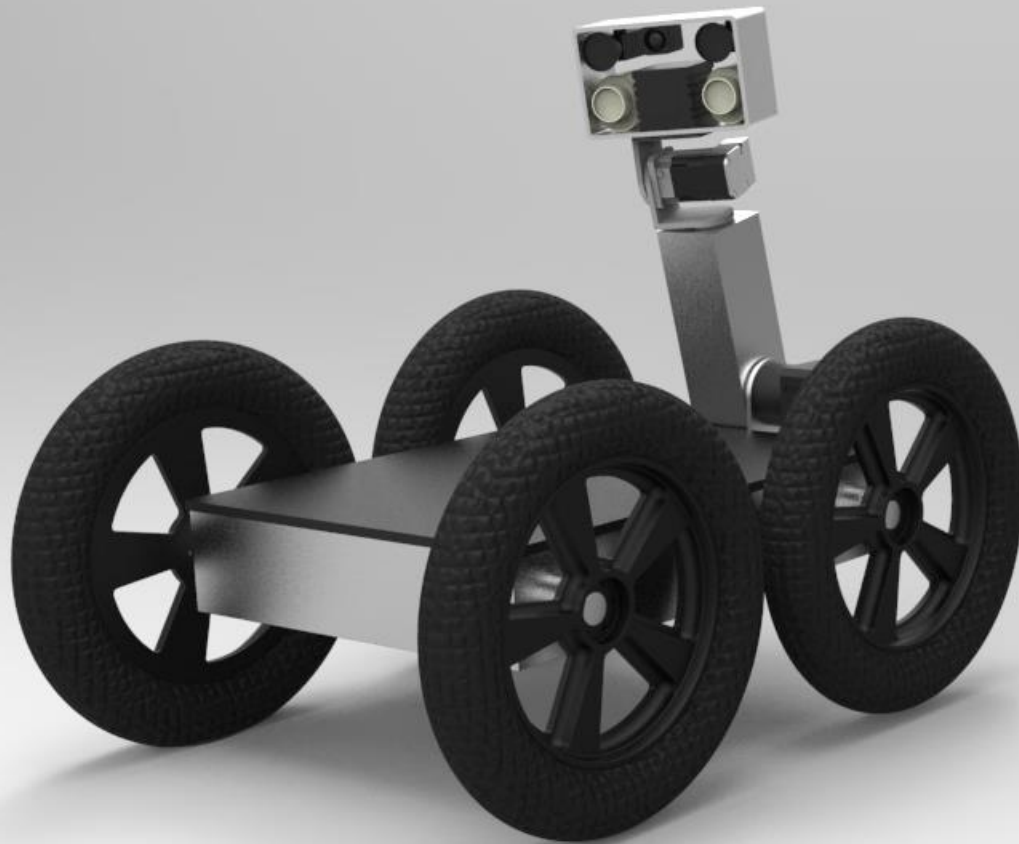
3DOF ARM

TANK-LIKE DRIVE

ROBUST CONSTRUCTION

ORPHEUS-AC2 DRIVE SYSTEM

Possible Missions



RECONNAISSANCE AND MAPPING

CBRNE

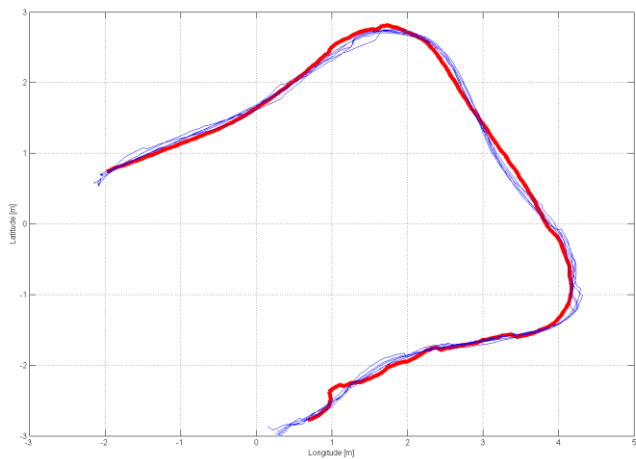
FIRE FIGHTING

MULTISPECTRAL MAPPING

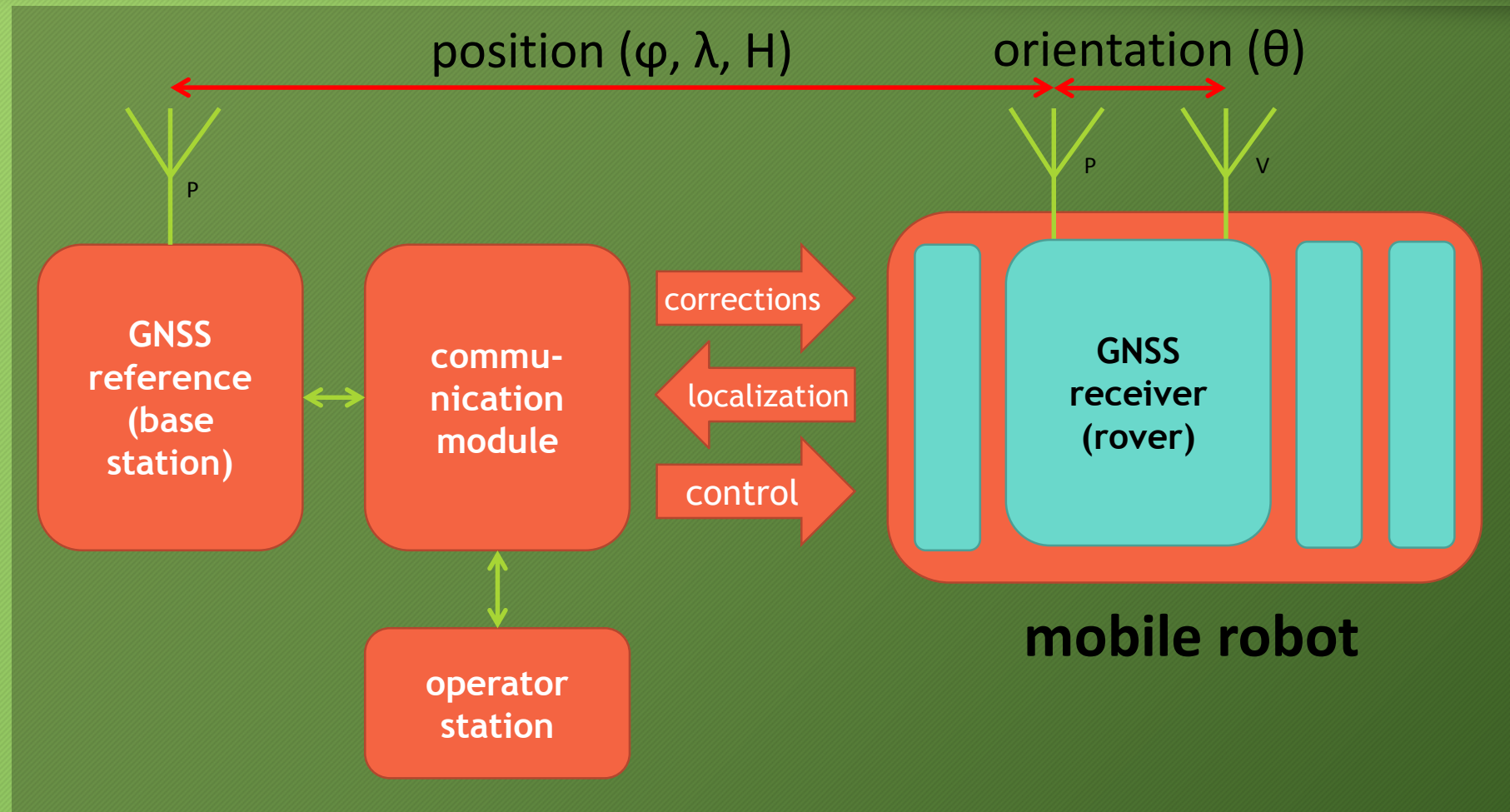
ENVIRONMENT MEASUREMENT

Outdoor Navigation - RTK GNSS

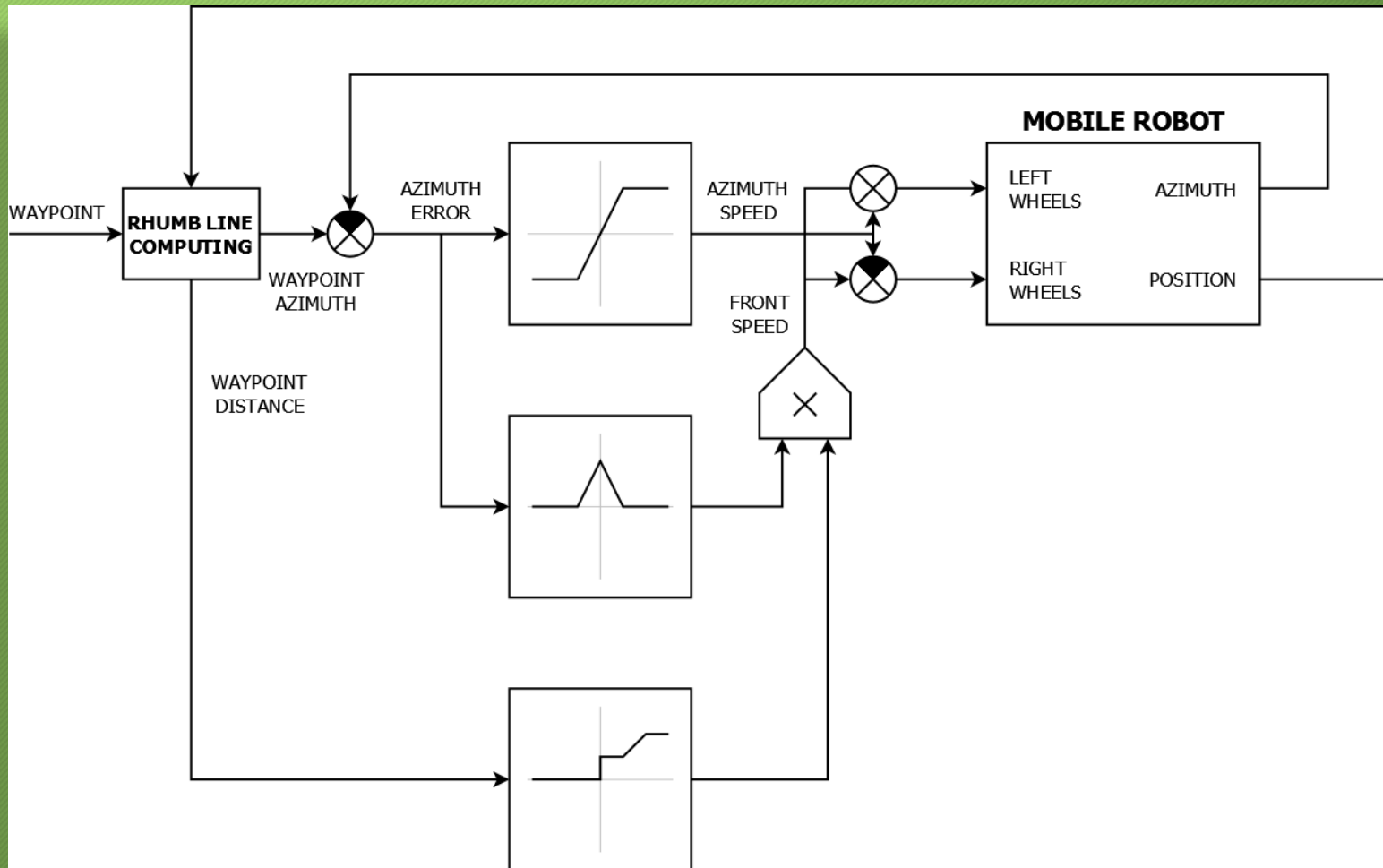
- GNSS with custom Base Station
- known precision
- also azimuth - RTK compass
- automatic waypoint generation
- automatic mission return



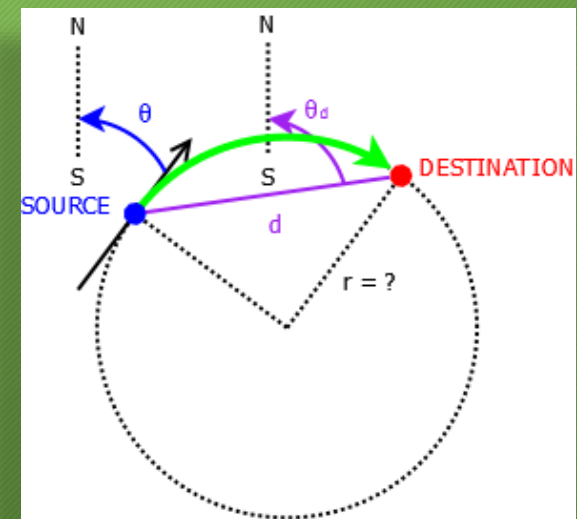
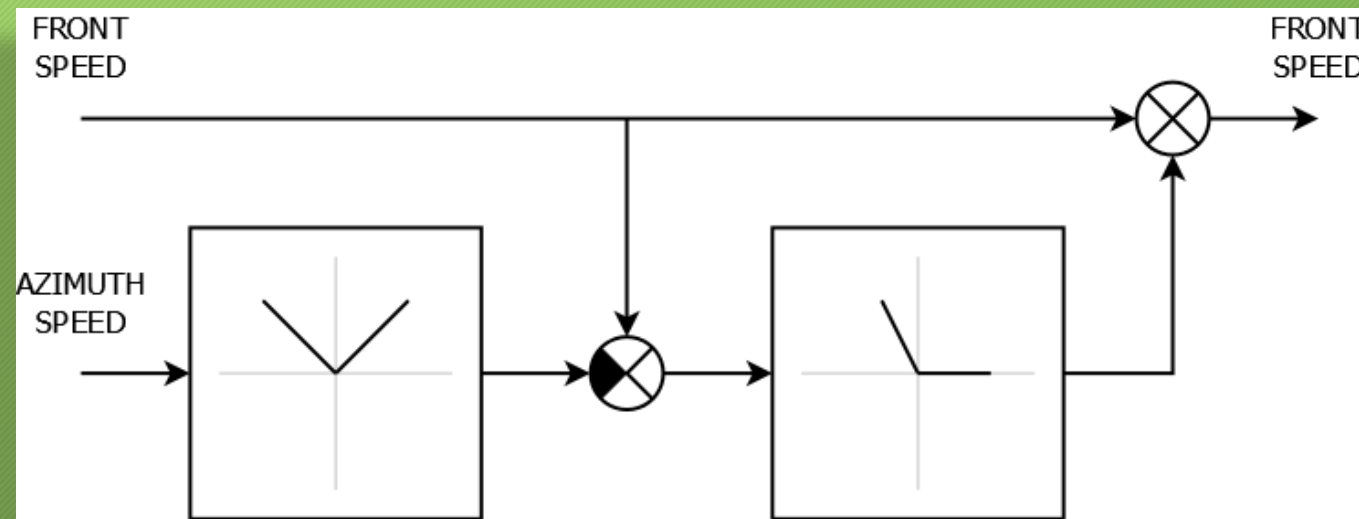
GNSS Scheme



Navigation Scheme



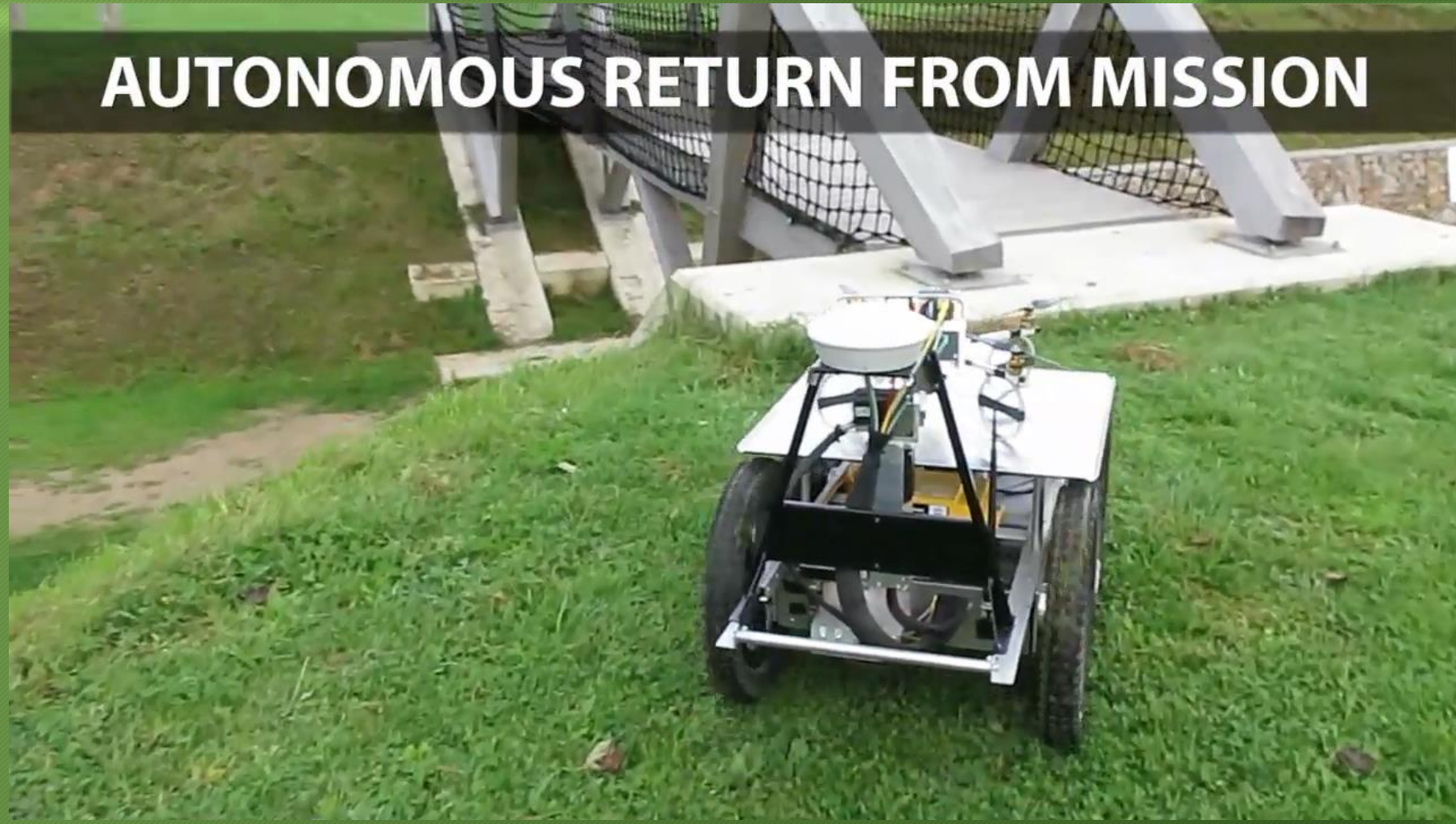
Momentum Reduction Scheme



Current Status - outdoor

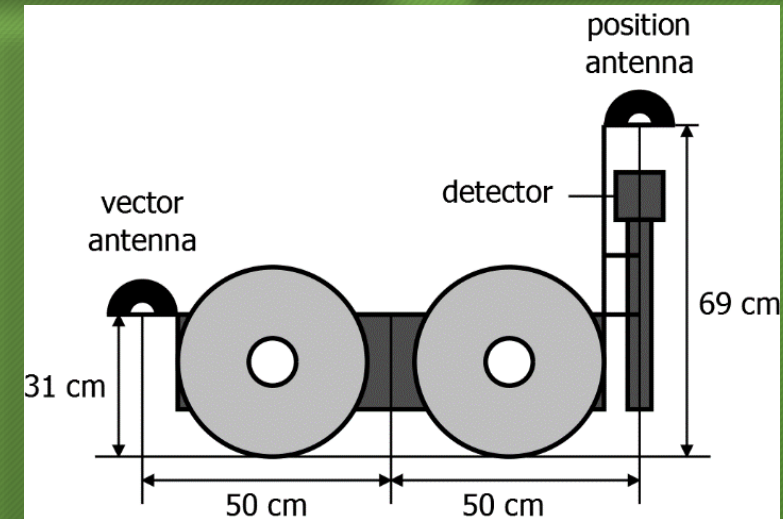
- ORPHEUS-X4 prototype and URANUS quadro
- robots may be combined to extend mission capabilities
- teleoperated and autonomous operation

AUTONOMOUS RETURN FROM MISSION



Orpheus-X3, modifications

- sensory head was deactivated
- steel/aluminum frame for GNSS antennas and scintillation radiation probe was constructed



Ground Radioactive Contamination Measurement Experiment



- TASK: measure La-140 isotope dust spread on grass-covered meadow
- Data Time-synchronization, position measurement only
- Operator control - no autonomous navigation

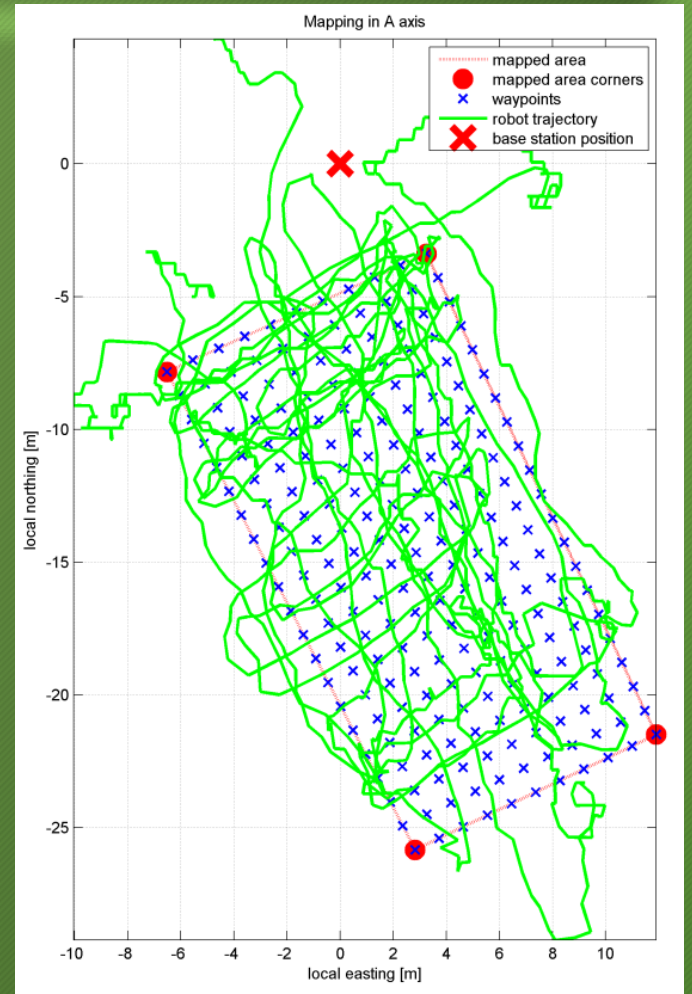
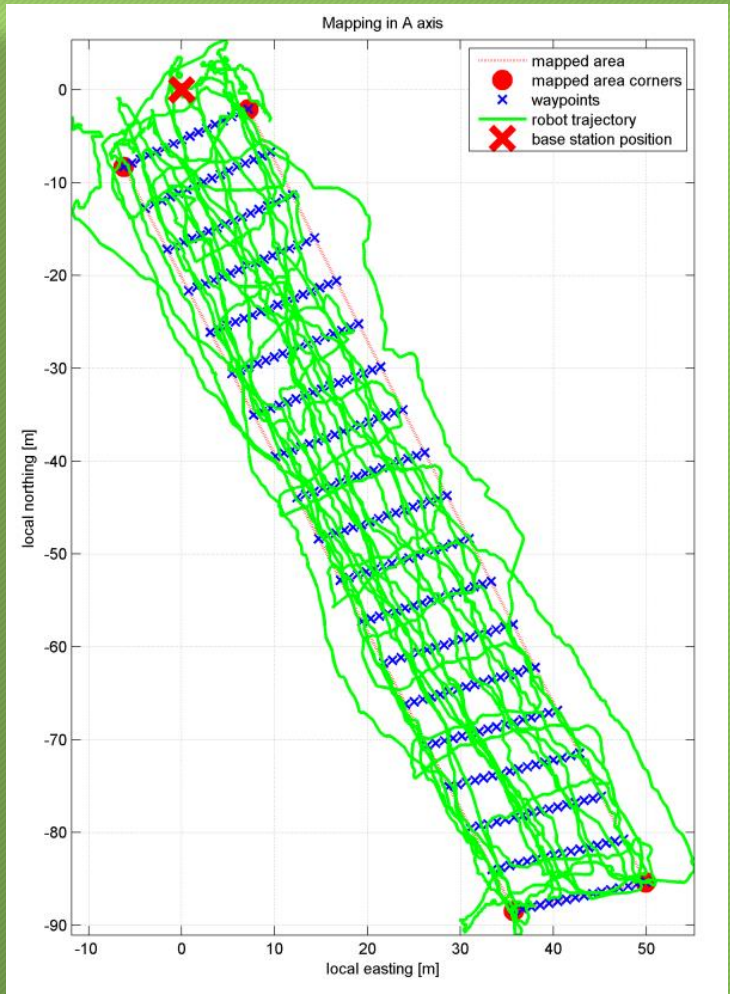


Lost Radiation Sources Experiment

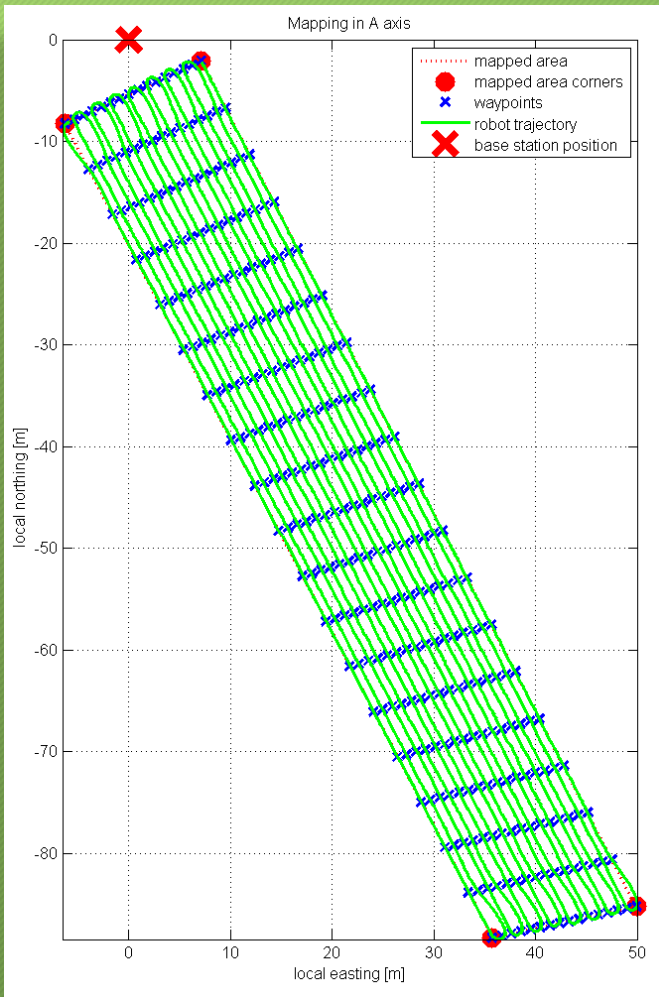
- TASK: Localize randomly located sealed radiation sources
- Two parts - greater area, and smaller area with more dense measurements
- Fully autonomous navigation and selflocalization



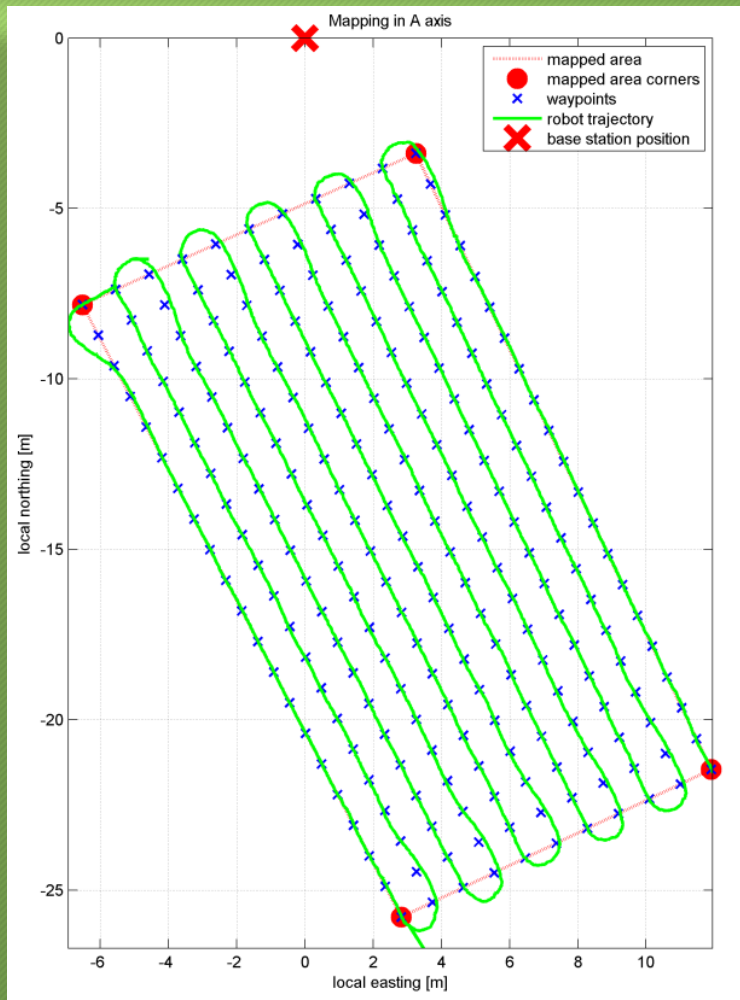
Experiment 2a - selfloc with "standard" L1 GPS



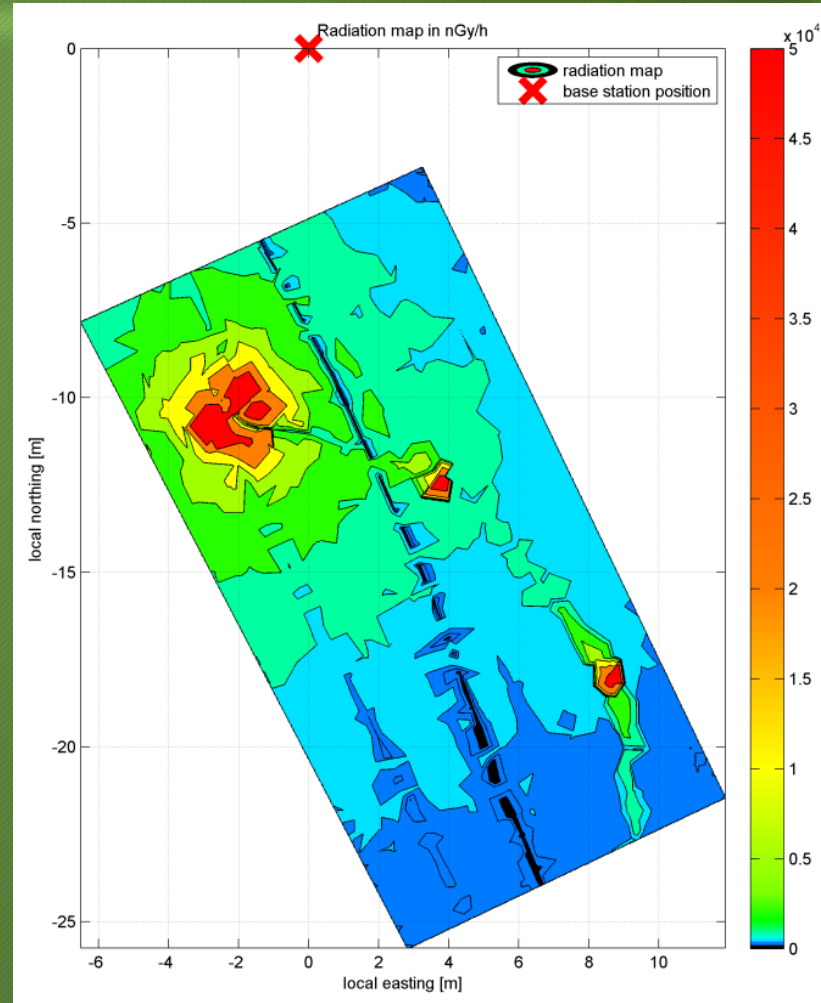
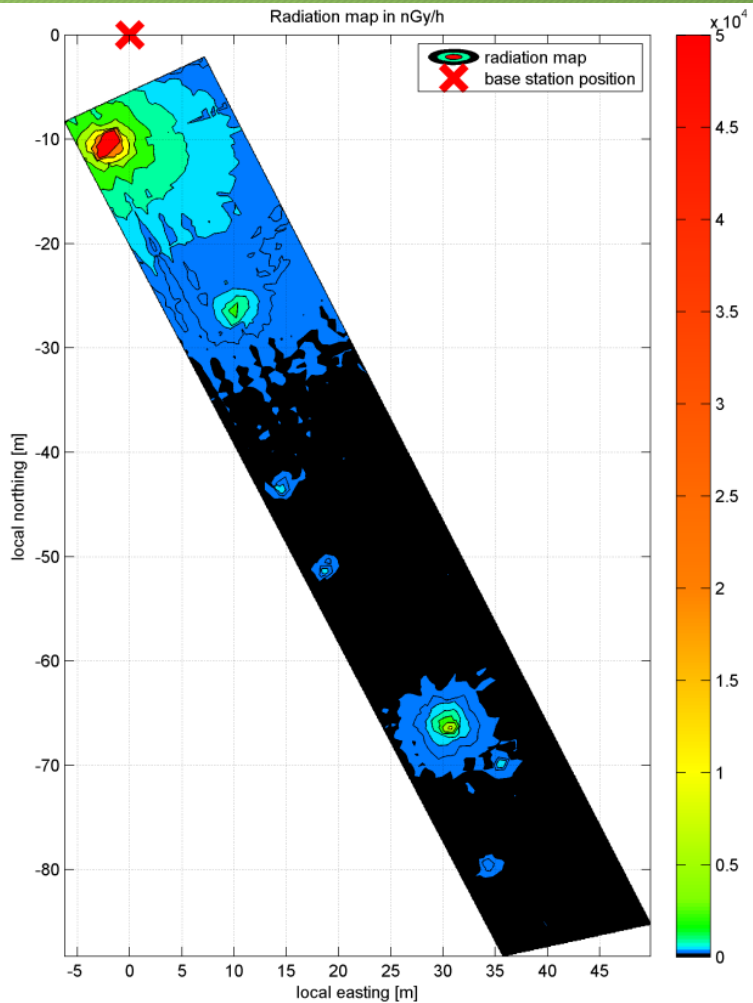
Experiment 2a - selfloc with RTK GNSS



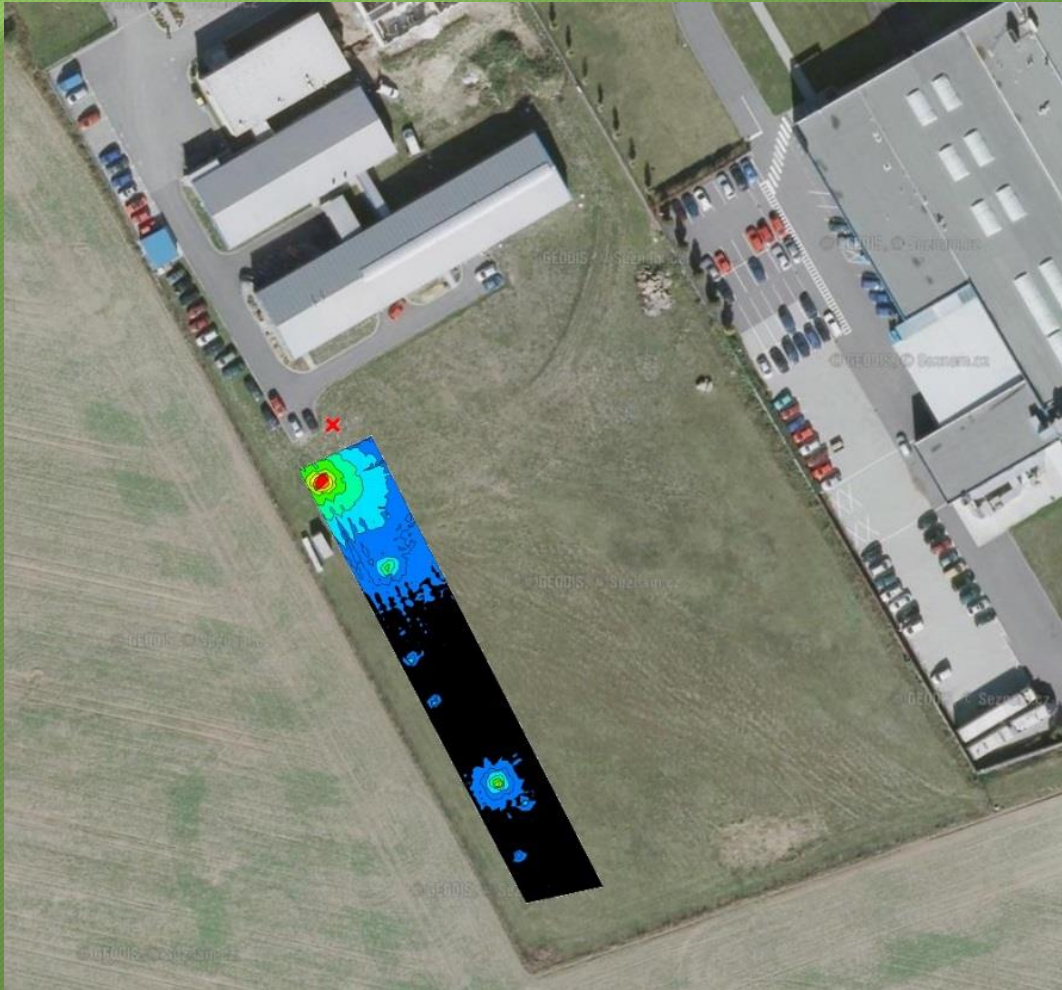
Experiment 2b - trajectory planning



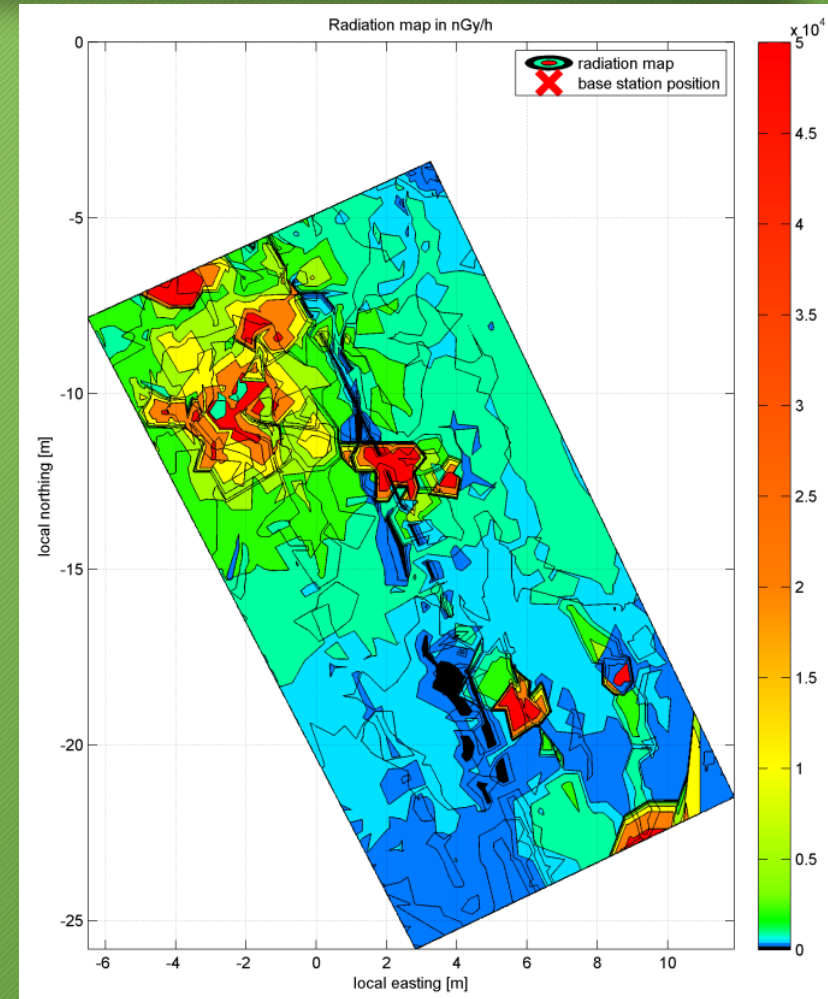
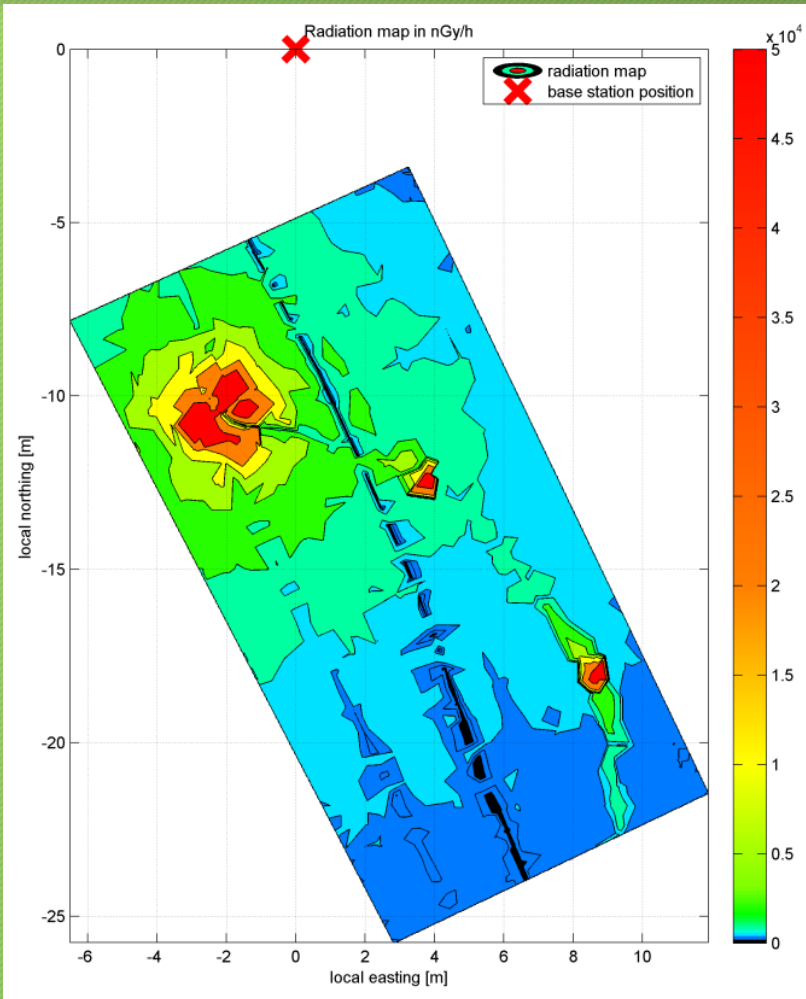
Radiation Intensity Map [nGy/h]



Radiation Intensity Aligned With Orthofoto Map



RTK GNSS and GPS L1 Map Comparison





THANK YOU FOR YOUR ATTENTION